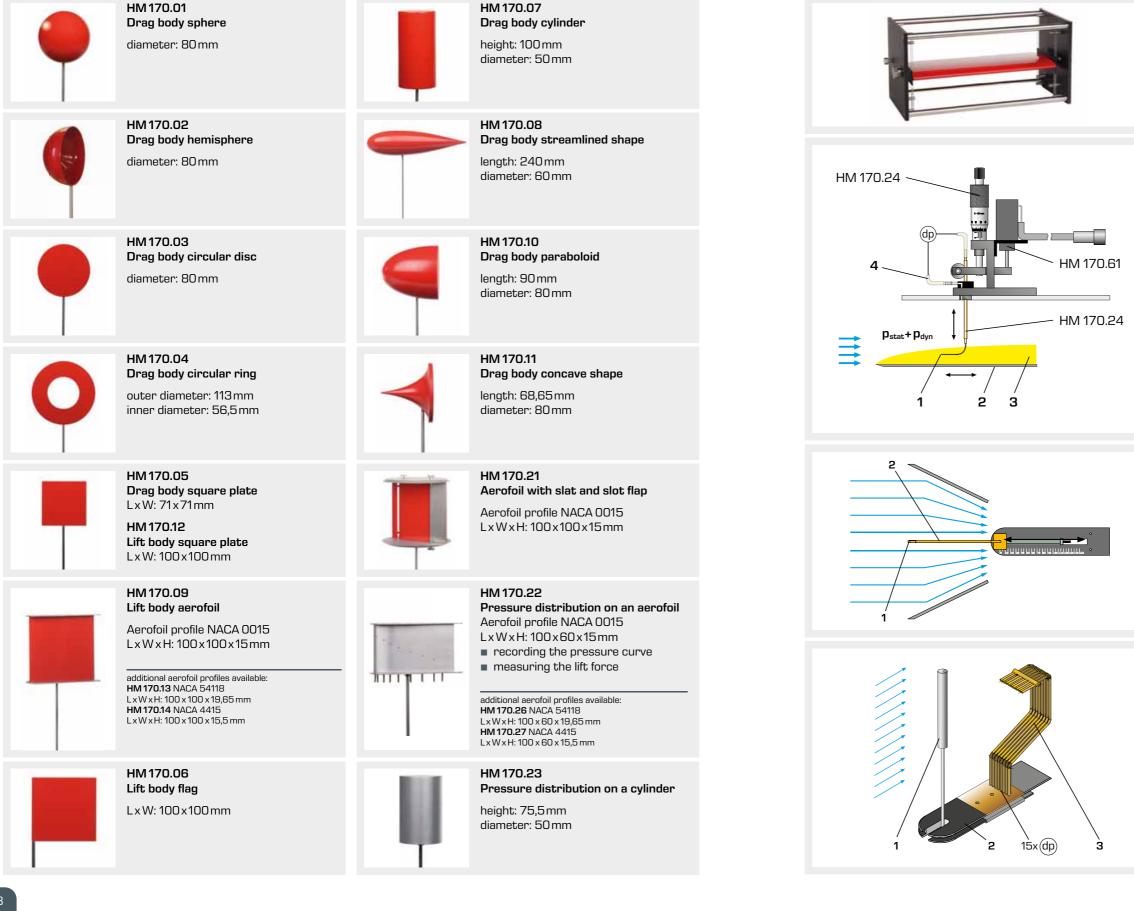
HM 170 Accessories for the wind tunnel





HM 170.20 Airfoil, spring-mounted Aerofoil profile NACA 0015 LxWxH: 200x100x15mm

transverse rigidity: 216 N/m
torsion rigidity: 0,07...0,28 Nm/rad

HM 170.24 Boundary layer analysis with Pitot tube

Two plates, rough and smooth, LxWxH = 279x250x3mm

- vertically movable Pitot tube measures the pressures at various distances from the plate surface
- horizontally movable plate for recording pressures along the flow
- displaying measured values on the PC using
- HM 170.60 System for data acquisition and
- HM 170.61 Electronic displacement measurement

Measuring pressures:

1 stagnation point at the Pitot tube (total pressure), 2 flat plate, 3 boundary layer, 4 measuring point for static pressure, dp differential pressure measurement

HM 170.61 Electronic displacement measurement

Displacement measuring range: 0...10mm

HM 170.25 Model "Bernoulli"

Air inlet: 292 mm, air outlet: 146 mm, opening angle 52°, Pitotstatic tube, outer diameter: 4 mm

 horizontally movable Pitotstatic tube
 wedge-shaped inserts forming a measuring section whose cross-section steadily narrows

Measuring pressures:

 $1\,$ stagnation point at the Pitotstatic tube (total pressure), $2\,$ Pitotstatic tube

HM 170.28 Wake measurement

Cylinder: D x H: 20 x 100mm Wake rake consists of 15 Pitot tubes, outer diameter: 2mm, distance between the Pitot tubes: 3mm

 display of measured values on tube manometers HM170.50 or on the PC using HM170.55 Electronic pressure measurement

Measuring pressures:

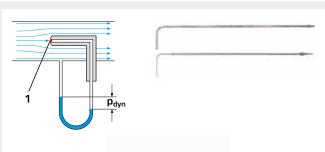
cylinder,

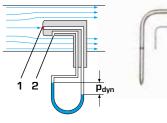
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- 2 bracket,3 wake rake,
- **dp** differential pressure measurement

HM 170 Accessories for the wind tunnel













HM 170.70 Wind power plant with rotor blade adjustment gearless wind power plant with 3-blade rotor, adjustable rotor blade angle via servo motor, investigation of own rotor blade shapes (3D printing) possible

- replaceable rotor blades with straight and optimised profile
- variable speed generator system
- recording of wind speed, rotor speed and generated electricity

1 connection for wind tunnel HM170, 2 flow straightener, 3 tower, 4 wind power plant, 5 protective cover

HM 170.31 Pitot tube

outer diameter: 4 mm

HM170.32 Pitot tube, small outer diameter: 2 mm

Determining the total pressure:

1 stagnation point The pressure in the stagnation point is equal to the total pressure

HM170.33 Pitotstatic tube outer diameter: 3 mm

Determining the dynamic pressure:

1 stagnation point, 2 measuring point for static pressure The difference between total and static pressure gives the dynamic pressure

HM 170.53 Differential pressure manometer

- differential pressure: 0...5 mbar
- graduation: 0,1mbar

HM170.50 16 tube manometers LxWxH: 670x220x750mm

- manometer inclination up to max. 1/10
- max. 600mmWC
- height-adjustable manometer
- individual zero points can be set

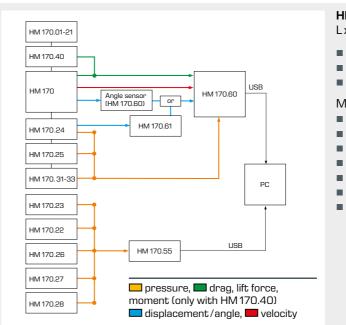
The tube manometer operates on the principle of communicating tubes

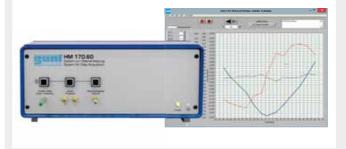
HM170.52 Fog generator LxWxH: 350x500x300mm

power consumption: 500W













HM 170.40 Three-component force sensor LxWxH: 370x315x160mm (measuring amplifier) DxH: 115x150mm (force sensor)

measuring amplifier with connections for forces and moment
 connection to HM 170.60 possible
 display of drag, lift and moment

Measuring ranges drag: ±4N lift: ±4N moment: ±0,5Nm

■ angle: ±180°

1 force sensor, 2 measuring amplifier

HM 170.55 Electronic pressure measurement for HM 170 LxWxH: 370x315x160mm

- ∎ 18 inputs, ±5mbar
- CD with GUNT software included
- data acquisition via USB under Windows

HM170.60 System for data acquisition LxWxH: 360x330x160mm (interface module)

- CD with GUNT software included
- data acquisition via USB under Windows
 angle sensor
- Measuring ranges
- displacement: 0...10 mm
- ∎ angle: ±180°
- differential pressure: ±5mbar
- velocity: 0...28m/s
- ∎ drag:±4N
- ∎ lift: ±4N
- moment: ±0,5Nm
- (only for HM 170.40 Three-component force sensor)